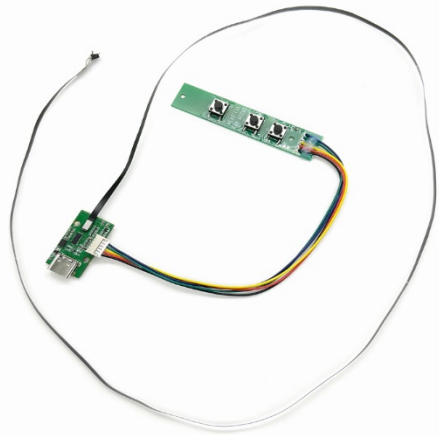


Introduction:

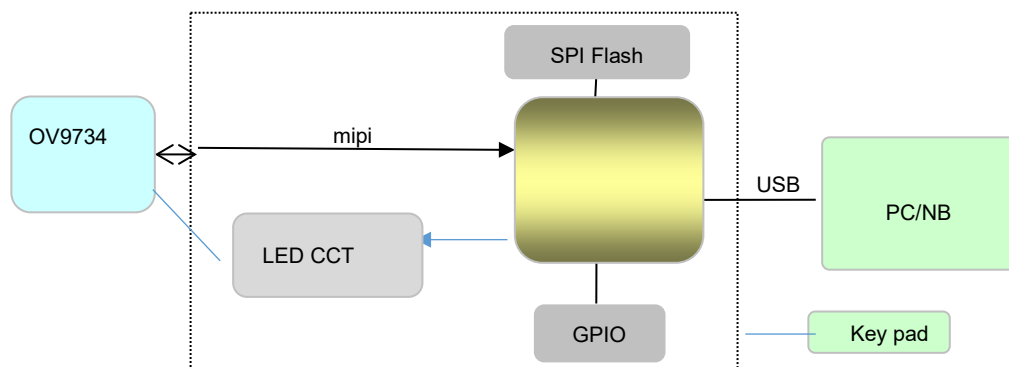
UCSPF1 is an advanced USB module with flexible OV9734 camera from COMedia Ltd. This module is not only compact in size, but also cost-effective. It is suitable for medical and industrial applications.

Key Features

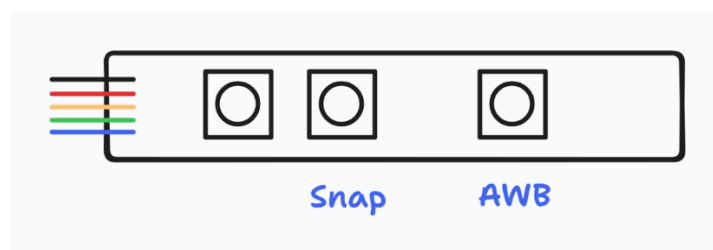
- ✓ Max Resolution:1280*720@30fps
- ✓ Interface: USB 2.0, type C connector
- ✓ Protocol: UVC, Plug & Play
- ✓ Power: 5V by USB port
- ✓ Built in LED driving circuit for camera tip LED
- ✓ Small in size (26mm x 14 mm)
- ✓ Snapshot and AWB Functions
- ✓ Flexible cable length 60/70cm
- ✓ Support mjpeg and YUY2 format



Block Diagram



GPIO and Keys Design



Electrical Characteristics

	Condition	Typ.	Unit
Operation voltage	Supply by PC USB port	5	V
Operation current	Video streaming	90	mA
Standby current	No streaming but plugged in PC	10	mA

Lens spec

Composition	4 elements
Effective focal length	0.75
F No	5.80
Back Focal length	1.08mm
TV Distortion	-20%
Relative illumination	51.5%@1.0f
IR cut filter	Built in

Operation

1. Preparation
 - a. Plug in flexible camera module, note the orientation of connector. Wrong polarity may cause damage of camera.
 - b. Plug in the key board, if available.
 - c. Connect to PC/NB thru USB cable with one end type C connector plug to the module
2. Preview in PC
 - a. Before you can preview video on PC screen, you need to have PC cam viewer, such as Amcap from Microsoft.
 - b. It is UVC compliance, no need to install driver manually but you need to wait a while when first time plug in the camera. It will install the right driver by itself. You will find there is USB camera listed in PC hardware manager after that.
 - c. When turn on the software, video will stream on the screen.
3. White balance calibration
 - a. To do white balance calibration, point the camera to a white target, press and hold AWB key, it will calibrate the color and make RGB channel balance. Release key in 2-3 seconds.
 - b. If it is under or over exposure, it may not do the calibration correctly.
4. Snapshot
 - a. Press once SNAP key, the module will get the image and send to the host thru UVC protocol. (need software support)

Mechanical Dimensions

